Game Reveal - FIRST Releases Game to the World

1. Information Gathering: Learn the game – Work Day 1

With no regards to strategy or design, team achieves mastery in understanding the game.

2. Strategy Phase – Work Day 2

- Consider what the robot is going to do & explicitly what the robot is not going to do.
- Functional Requirements: metrics of success are documented. These must be testable.
- After whole team discussion, game play strategy is decided by the Desicion Voting Council (DVC).

3. Design Phase – Work Day 3 – 13

- Work begins on one (or multiple) alpha bots
- Robot is compartmentalized into various discrete subsystems (as best as possible)
- Any predetermined subsystems created before build season are briefly reviewed & finalized for approval to step 4. Depending on human resource allocation hardware & software are started as soon as possible.



- CAD nearly complete robot to fully visualize design
- Critical Design Review (CDR) of full robot Final designs decided by DVC
- Precision Mechanical Design Review: Smaller, more refined group of mechanical engineering students & mentors review detailed hardware components for integrity & proper placement. CAD is updated to reflect changes.

4. Build Phase – Work Day 6 - 36

Software
 Design top level architecture
Define tasks & subtasks
Write task/subtask code
☆ Integrate → test on simulations → debug → optimize code
Document & comment for user ease
Deploy & continued maintenance

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Prototype

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- Integration Testing: run code & test hardware & software task integration
- Validate robot strategy & functional requirements
 - Revisit step 3 or 4 if functional requirements are not met or any subystems do not work. Careful consideration to personnel time and material resources if proposing major changes



6. Practice Game, Refine Human Player & Optimize Hardware & Software – Work Day 8 - 37

- Simulate game & human player practice
 - > Drive team & Pit team practice all roles (strategy, scouters, drivers, operations, pit managers, etc.)
 - Continuous & repeated driver/operator teleop practice
- Autonomous Practice: routines finalized
- Hardware & software continually optimized to meet or exceed functional requirements

